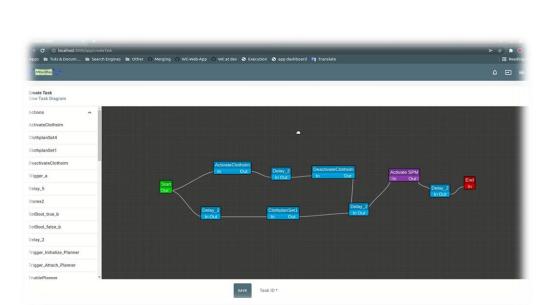


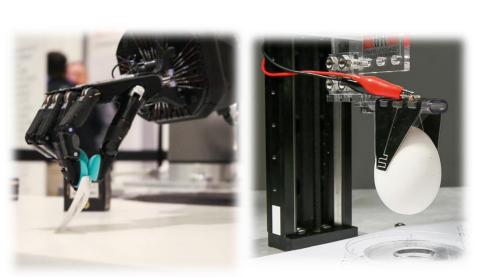
H2020-EU.2.1.5.1. Technologies for Factories of the Future

Manipulation Enhancement through Robotic Guidance and Intelligent Novel Grippers

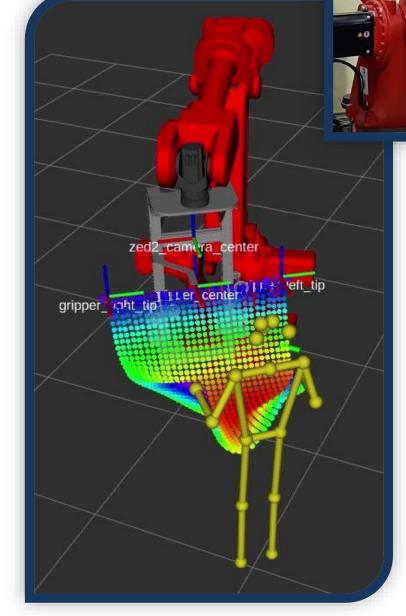
Deformable object handling controller



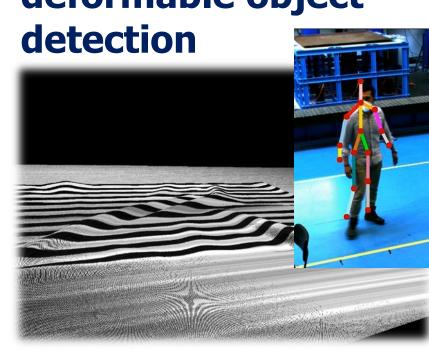
EA enhanced dexterous & versatile gripping



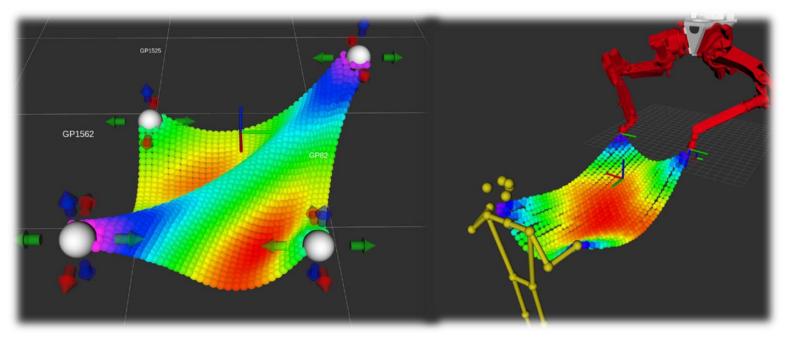
Workcell digital representation



Robot perception and deformable object



Flexible material modelling and simulation



Robot easy programming, adaptive and collaborative



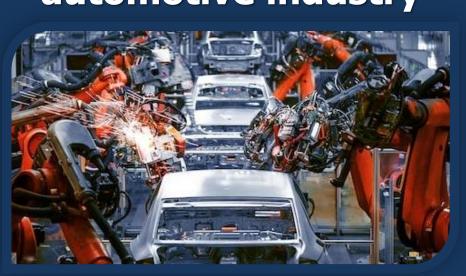
Textile and garment industry



Food packaging industry



Composites for automotive industry



Coordinated by











